

# CSCC73 – Algorithm Design and Analysis

Fall 2018 Finals Notes – Anna Bretscher

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**Dijkstra's Algorithm**  $O(E + V \log V)$   
Greedy, uses a vertex set  
Finds the shortest path from a source node (s) to every other node (t)

**Prim's Algorithm**  $O(E \cdot \log V)$   
Greedy, uses a min heap  
Finds a Minimum Spanning Tree  
- graph must be connected, otherwise only 1 of several MSTs are found  
- better for dense graphs due to nature of fibonacci heap

**Kruskal's Algorithm**  $O(E \cdot \log V)$   
Greedy, uses disjoint sets  
Finds a Minimum Spanning Tree  
- if graph is non-connected, finds minimum spanning forest  
- better for sparse graphs

**Tree theorem:** Need to prove that an MST is a tree

**Cut Theorem:** Need to prove that greedily choosing the smallest edge at each iteration of the algorithm, will result in an MST.

**Huffman Encoding**  
Greedy, tree data structure to store encoding  
Finds the optimal smallest bit representation of strings by sorting by ascending usage rate and constructing intermediate trees

**Bellman-Ford's algorithm**  $O(VE)$   
Dynamic Programming, uses vertex set  
Finds the shortest path from a single node (s) to every other node (t)  
- Can detect negative cycles in graph  
- Can deal with negative weight edges and negative cycles

**Floyd-Warshall's Algorithm**  $O(V^3)$   
Dynamic Programming, uses vertex set  
Finds all-pairs shortest path in a graph  
- shortest path length for all u, v in graph  
- doesn't store the details of the path length  
- can deal with negative weights  
- cannot deal with negative cycles

**Ford-Fulkerson's Algorithm**  $O(Ef)$   
Greedy, done by running augmenting paths on residual graph  
Finds the maximum network flow in a graph

**Min-cut is max flow** – the minimum cut of a graph is equivalent to its max flow

**Hall's Theorem**  
Hall's Marriage Theorem states for any G bipartite graph containing the partition  $V_1, V_2$  st.  $|V_1| = |V_2|$  there is a perfect pairing iff  
 $|N(X)| > |X|$  for any subset X

That is, any subset of the smaller bipartite graph has a neighbourhood (edges to other nodes) larger than the number of elements

**Johnson's Algorithm**  
Finds all-pairs shortest paths  
Add new vertex s, add edges from G to s, becoming G'. Run Bellman-Ford on G' using s as source finding a positive weighted edge for every pair. Remove added vertex and run Dijkstra's on every vertex  
- Needs fibonacci heap to run better than F-W  
- Worse on dense graphs  
- Can deal with negative weight edges and negative cycles

**Simplex Method/Tableau**  
1. Set up slack variables  $s_1, s_2, \dots, s_n$   
2. Transform into standard form,  $z - nx_1 - mx_2 \dots = 0$   
3. Set up matrix such that  
4. Use row-reduction to solve, when all  $x_1 \dots x_n$  are  $\geq 0$ , then we have our answer

**Dual LP**  
Create coefficients and use them to find a new LP  
Solve that LP to find the constraints on the primal LP  
Related that Primal is Maximization, Dual is Minimization  
Is extended from same proof that Max Flow = Min Cut

$$\begin{array}{c|cccccc|c} z & z & x_1 & x_2 & s_1 & s_2 & s_3 & b \\ \hline 1 & 1 & 0 & 0 & 1.6 & 2.2 & 0 & 544 \\ s_1 & 0 & 1 & 1 & 0.4 & -0.2 & 0 & 16 \\ s_2 & 0 & 0 & 1 & -0.2 & 0.6 & 0 & 72 \\ s_3 & 0 & 0 & 0 & -0.4 & 0.2 & 1 & 19 \end{array}$$

# Algorithms and Applications

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## Greedy Algorithms

Greedy Stays Ahead and Exchange Argument – usually  $O(n \log n)$  due to some well-ordered sorting that exposes optimal sol'n

**Scheduling Problem** –  $O(n \log n)$

**Q:** Schedule max amount of jobs to be completed

**A:** Sort the jobs by earliest end time and take greedily take each end time that doesn't conflict – exchange argument

**Interval Partitioning** –  $O(n \log n)$

**Q:** Schedule min amount of rooms to accommodate all meetings

**A:** Sort lecs by start time, if can be scheduled do it, otherwise open new room – greedy stays ahead

**Shortest Paths in a Graph** –  $O(E + V \log V)$

**Q:** Find the shortest path between two nodes  $u, v$

**A:** Run Dijkstra's algorithm, greedily taking the shortest edge not in the solution at each step – greedy stays ahead

**Minimum Spanning Tree** –  $O(E \cdot \log V)$

**Q:** Find a tree which visits every node but has the least total path weight

**A:** Use Prim's or Kruskal's algorithms, greedily taking by the cut theorem the upcoming edge – exchange argument

**Huffman Encoding**

**Q:** Finding a minimal bit representation of any string – the optimal prefix codes

**A:** Using Huffman encoding, we greedily take lowest priority characters and construct a tree from them – exchange argument

**Knapsack Problem** – **Fractional** is greedy, simply choose the best (ratio) item continuously, then continue to next item, etc.

## Divide and Conquer

Divide into subproblems and recombine into answer – using recurrence relations and bounding runtime Master Theorem

**Counting Inversions** – divide into two until base case, merge step counts from  $1..n$  on both arrays, counting inversions at each step

**Closest Pairs** – divide into two parts until base case, find smallest distance  $d_1$ , create zone of  $d_1$  around division, find smallest  $d_2$  in that zone, the smallest pair in this subproblem is  $\min(d_1, d_2)$

**Integer Multiplication** – convert to binary, into  $n/2$  high and  $n/2$  low bits, becomes a shift – recursive multiply theorem

**Matrix Multiplication** – divide  $a/b$  into  $n/2$  blocks, conquer by multiplying the  $8 n/2$  blocks recursively, combine by adding **Strassen's Al.**

## Dynamic Programming

Divide into optimality of previously solved (memoized) subproblems – proven using star (description), dagger (recurrence)

**Weighted Interval Scheduling** – scheduled jobs have weights, we take  $\max(v_j + M[p_j], M[j - 1])$

**Knapsack Problem 0-1** – thief must choose to take or leave the item, having recurrence of  $\max(\text{Opt}(i - 1, w), v_i + \text{Opt}(i - 1, w - w_i))$

**Sequence Alignment** – define gap penalty, can model as a DAG and use **Hirschberg's Algorithm**

**All-Pairs / Shortest Path** –

Floyd Warshall's Algorithm – distance array, SP between nodes,

Bellman-Ford's Algorithm – finds the optimal edges by selecting shorter paths and working upwards

**Optimal BSTs**

**Longest Common Subsequence** - Given two strings  $X, Y$ , find the longest common subsequence of characters  $O(N M)$

**Longest Increasing Subsequence** - Given an unsorted array  $A$ , find the longest increasing subsequence of characters  $O(N^2)$

**Maximum Independent Set** - Find set in a path  $G$ , with largest weight and no adjacent nodes  $O(N)$

## Network Flow

Finding the maximum flow of a network through setting up network, applying concepts like Residual Graph, Augmented Paths

**Bipartite Graph Matching** – create source to all  $V_1$ , sink to all  $V_2$  with capacities of 1, find if there exists a max flow equal to  $|V_1|$

**Disjoint Paths** – create source to all  $V_1$  and sink to all  $V_2$  all edges  $w/\text{cap } 1$ , then the number of disjoint paths is max flow to sink

**Network Connectivity** – **disconnect** if set of edges are used in all  $s, t$  paths

**Menger's Theorem** - The max number of edge-disjoint  $s, t$ -paths is equal to the minimum number of edges whose removal disconnects  $t$  from  $s$

**Circulation Problem** - we create  $S$  to all suppliers with pos capacity equal to their demand, and sink  $T$  to all retailers'  $w/\text{edges equal}$

## Linear Programming

Optimal answer to objective function subject to some linear constraints. Know Simplex Method, Tableau, and concept of Duality

**Max Flow** can be a LP problem

**Vertex Cover/MIS** can be a LP problem

**Shortest paths** can be a LP problem

**Slack Variables** are used to convert from  $\leq$  and  $\geq$  to  $=$